

# Lecture 1

A *time series* is a set of observations  $(x_t)$ , each one being recorded at a specific time  $t$ . This type of data appears naturally in everyday life, for example in:

- Medicine: heartbeat of a healthy person;
- Economics and Finance: stock prices at the end of the day;
- Demographics: population per year;
- Transport: international air traffic.

The purpose of the first part of the course is to present techniques for modeling these observations, i.e. the aim is to suggest a probabilistic model to represent the data. We think of  $x_t$  as the output of a stochastic process at time  $t$ .

**Definition 1.** Let  $T \subset \mathbb{R}$  be a time set, i.e. if  $t, s \in T$  then  $t+s \in T$ . A family  $X = (X_t)_{t \in T}$  of random variables on some probability space  $(\Omega, \mathcal{A}, \mathbb{P})$  is a stochastic process. For  $T \in \{\mathbb{N}, \mathbb{Z}\}$ ,  $X$  is called time series.

**Remark 1.** A time series is a mathematical sequence, not a series. A time series is an infinite sequence

$$\dots, X_{t_1}, \dots, X_{t_n}, \dots \quad t_i \in \mathbb{Z} \text{ or } t_i \in \mathbb{N}$$

of random variables (or random vectors).

The aim of the probabilistic modeling behind a time series is

- understanding of the stochastic system;
- predicting the future, i.e. predicting  $X_{t_{n+1}}$  given the observations  $(X_{t_1}, \dots, X_{t_n})$ ;
- drawing inference.

To achieve these tasks it is necessary to assume some a-priori structure of the time series otherwise any conclusion about the joint distribution of  $(X_{t_1}, \dots, X_{t_n})$  would be possible. A basic type of structure is stationarity.

**Definition 2.**  $X = (X_t)_{t \in T}$  is strictly stationary if

$$\forall n \in \mathbb{N}, t_1, \dots, t_n, t \in T \quad \mathcal{L}((X_{t_1}, \dots, X_{t_n})) = \mathcal{L}((X_{t_1+t}, \dots, X_{t_n+t})),$$

i.e.  $\forall A \in \mathcal{B}(\mathbb{R}^n): \mathbb{P}((X_{t_1}, \dots, X_{t_n}) \in A) = \mathbb{P}((X_{t_1+t}, \dots, X_{t_n+t}) \in A)$ .

Loosely speaking,  $X$  is stationary if its statistical properties do not change with time.

**Definition 3.**  $X = (X_t)_{t \in T}$  is weakly stationary (second order stationary) if  $\mathbb{E}[X_t^2] < \infty$  for all  $t \in T$ , the expectation function  $t \rightarrow \mu(t) := \mathbb{E}[X_t]$  is constant and the covariance function satisfies  $\text{Cov}(X_u, X_s) = \text{Cov}(X_{u+t}, X_{s+t})$ ,  $\forall u, s, t \in T$ .

For a weakly stationary series  $X$  we use the following vocabulary:

- Autocovariance at lag  $h$ :  $c(h) := \text{Cov}(X_{t+h}, X_t)$ .
- Autocorrelation at lag  $h$ :  $\rho(h) := \rho(X_{t+h}, X_t) = \frac{c(h)}{c(0)}$ .

**Example 1.** If  $X = (X_t)_{t \in T}$  are i.i.d., then  $X$  is strictly stationary.

**Example 2.** If  $X$  is in  $L_2$  (i.e.  $\mathbb{E}[X_t^2] < \infty$ , for all  $t \in T$ ) and it is strictly stationary, then  $X$  is weakly stationary.

Many time series in real life are not stationary but they can often be transformed in a time series that is (assumed to be) stationary. Indeed, the “classical decomposition” model is

$$X_t = m_t + s_t + Y_t,$$

where

- $m_t$  is a slowly changing function called the *TREND COMPONENT*;
- $s_t$  is a function with known period called the *SEASONAL COMPONENT* (e.g. weaker temperature in winter than in summer);
- $Y_t$  is a stationary time series.

Given  $x_t = X_t(\omega)$ , a realization of  $X$ , there are techniques to extract the deterministic components  $m_t$  and  $s_t$  so we are only left to study the residual  $Y_t$ .

If  $X$  is a weakly stationary process then its mean  $\mu$  and autocovariance function  $c$  contribute to characterize it. However,  $\mu$  and  $c$  are generally unknown quantities, they need to be estimated from the data.

### Estimation of $\mu$ and $c$

**Reminder 1.** Let  $\mathcal{P} = (\mathcal{X}, \mathcal{F}, (P_\theta : \theta \in \Theta))$  be a statistical model and  $X_1, \dots, X_n$  be random variables defined on  $(\mathcal{X}, \mathcal{F})$ . An estimator  $\hat{\theta}$  of the unknown parameter  $\theta \in \Theta$  from realizations  $x_1, \dots, x_n$  of  $X_1, \dots, X_n$  is a measurable function of  $X_1, \dots, X_n$ , i.e.

$$\hat{\theta} = \hat{\theta}(X_1, \dots, X_n) \quad \text{is a random variable.}$$

Good estimators are estimators that enjoy nice properties:

- $\hat{\theta}$  is an unbiased estimator of  $\theta$  if  $\mathbb{E}_\theta[\hat{\theta}] = \theta$ , for all  $\theta \in \Theta$ .
- $\hat{\theta}$  is a consistent estimator of  $\theta$  if  $\forall \varepsilon > 0 \ P_\theta(|\hat{\theta} - \theta| > \varepsilon) \rightarrow 0$  as  $n \rightarrow \infty$ , for all  $\theta \in \Theta$ .

- If  $\hat{\theta}$  and  $\theta^*$  are unbiased estimators of  $\theta$  we say that  $\hat{\theta}$  is more effective than  $\theta^*$  if  $\text{Var}_\theta(\hat{\theta}) \leq \text{Var}_\theta(\theta^*)$ .

If nothing is known about the distribution of the time series  $X$ , besides that it is stationary, then the natural estimators for  $\mu$  and  $c$  are their sample counterparts:

$$\hat{\mu}_n := \frac{1}{n} \sum_{i=1}^n X_i, \quad \text{empirical mean (sample mean)}$$

$$\hat{c}(k) := \frac{1}{n} \sum_{l=1}^{n-k} (X_l - \hat{\mu}_n)(X_{l+k} - \hat{\mu}_n), \quad \text{empirical autocovariance function at lag } k.$$

Set  $\hat{c}(-k) = \hat{c}(k)$ . The *empirical autocovariance matrix* is

$$\hat{C}_n = \begin{pmatrix} \hat{c}(0) & \hat{c}(1) & \dots & \hat{c}(n-1) \\ \hat{c}(1) & \ddots & \ddots & \hat{c}(n-2) \\ \vdots & \ddots & \ddots & \vdots \\ \hat{c}(n-1) & \dots & \hat{c}(1) & \hat{c}(0) \end{pmatrix}.$$

Observe that  $\hat{C}_n$  is a Toeplitz matrix.

### Properties of $\hat{\mu}_n$

**Theorem 1.** Let  $(X_t)_{t \in \mathbb{Z}}$  be a weakly stationary process with autocovariance function  $c$  and mean  $\mu$ , then for the sample mean  $\hat{\mu}_n$  the following properties hold:

1. (Unbiasedness)  $\mathbb{E}[\hat{\mu}_n] = \mu$ ;
2. (Variance)  $\text{Var}[\hat{\mu}_n] = \frac{1}{n} \sum_{k=-n+1}^{n-1} \left(1 - \frac{|k|}{n}\right) c(k)$ ;
3. (Consistency) If  $c(k) \xrightarrow[k \rightarrow \infty]{} 0$ , then  $\mathbb{E}[(\hat{\mu}_n - \mu)^2] \rightarrow 0$ ;
4. (Asymptotic variance) If  $\sum_{k=-\infty}^{\infty} |c(k)| < \infty$  then  $n \text{Var}(\hat{\mu}_n) \rightarrow \sum_{k=-\infty}^{\infty} c(k)$ .

*Proof.* 1.  $\mathbb{E}[\hat{\mu}_n] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[X_i] = \frac{n\mu}{n} = \mu$ .

2. Using that  $(\text{Cov}(X_i, X_j))_{i,j}$  is a Toeplitz matrix we have:

$$\begin{aligned} \text{Var}(\hat{\mu}_n) &= \frac{1}{n^2} \text{Var}\left(\sum_{i=1}^n X_i\right) = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \text{Cov}(X_i, X_j) = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n c(i-j) \\ &= \sum_{k=-(n-1)}^{n-1} \frac{n-|k|}{n^2} c(k) = \frac{1}{n} \sum_{k=-n+1}^{n-1} \left(1 - \frac{|k|}{n}\right) c(k). \end{aligned}$$

3. To prove that  $\hat{\mu}_n$  is a consistent estimator of  $\mu$  it is enough to prove that  $\mathbb{E}[(\hat{\mu}_n - \mu)^2] \rightarrow 0$  since convergence in  $L_2$  implies convergence in probability. We have

$$\begin{aligned}\mathbb{E}[(\hat{\mu}_n - \mu)^2] &= \text{Var}(\hat{\mu}_n) = \frac{1}{n} \sum_{k=-n+1}^{n-1} \left(1 - \frac{|k|}{n}\right) c(k) \leq \frac{1}{n} \sum_{k=-n+1}^{n-1} |c(k)| \\ &= \frac{2n-1}{n} \left( \frac{1}{2n-1} \sum_{k=-(n-1)}^{n-1} |c(k)| \right) \rightarrow 0\end{aligned}$$

by Cesàro mean theorem using that  $c(k) \rightarrow 0$ .

4. Using the Dominated Convergence Theorem (DCT) we have

$$\lim_{n \rightarrow \infty} n \text{Var}(\hat{\mu}_n) = \lim_{n \rightarrow \infty} \sum_{k=-n+1}^{n-1} \left(1 - \frac{|k|}{n}\right) c(k) = \sum_{k \in \mathbb{Z}} c(k).$$

□

**Remark 2.** Let  $X$  be a weakly stationary time series with mean  $\mu$  and autocovariance function  $c$ . Thanks to Theorem 1 we know that if  $\sum_{k \in \mathbb{Z}} |c(k)| < \infty$  then  $\sqrt{n}(\hat{\mu}_n - \mu)$  is bounded in  $L_2$  and hence in probability. We can thus conclude that the rate of convergence of  $\hat{\mu}_n$  to  $\mu$  is  $\sqrt{n}$ .

**Remark 3.** Under suitable conditions, the sample mean  $\hat{\mu}_n$  of a weakly stationary process  $X$  satisfies:

$$\sqrt{n}(\hat{\mu}_n - \mu) \rightarrow \mathcal{N}\left(0, \sum_{k \in \mathbb{Z}} c(k)\right). \quad (1)$$

Provided that one is able to estimate the asymptotic variance  $\sum_{k \in \mathbb{Z}} c(k)$ , (1) allows to give confidence intervals. If in addition  $X$  is Gaussian, then

$$\mathcal{L}(\sqrt{n}(\hat{\mu}_n - \mu)) = \mathcal{N}\left(0, \sum_{|k| < n} \left(1 - \frac{|k|}{n}\right) c(k)\right), \quad \forall n.$$

### Properties of $c(k)$ and $\hat{c}(k)$

**Lemma 1.** The autocovariance function  $c : \mathbb{Z} \rightarrow \mathbb{R}$  of a weakly stationary process  $X = (X_t)_{t \in \mathbb{Z}}$  satisfies

1.  $c$  is symmetric:  $c(k) = c(-k)$  for all  $k \in \mathbb{Z}$ .
2.  $c(0) \geq 0$  and  $|c(k)| \leq c(0)$ .
3.  $c$  is positive semi-definite:

$$\forall m \in \mathbb{N}, a_1, \dots, a_m \in \mathbb{R} : \sum_{i,j=1}^m a_i a_j c(i-j) \geq 0.$$

*Proof.* 1. Since  $X$  is weakly stationary  $\text{Cov}(X_{s+k}, X_s) = \text{Cov}(X_r, X_{r-k})$ . Therefore,

$$c(k) = \text{Cov}(X_{s+k}, X_s) = \text{Cov}(X_r, X_{r-k}) = c(-k).$$

2. It is enough to observe that

$$c(0) = \text{Cov}(X_s, X_s) = \text{Var}(X_s) \geq 0, \quad \forall s \in \mathbb{Z}$$

and that, using Cauchy-Schwarz,

$$c(k)^2 = \text{Cov}(X_k, X_0)^2 = (\mathbb{E}[(X_k - \mu)(X_0 - \mu)])^2 \leq \text{Var}(X_k)\text{Var}(X_0) = c(0)^2.$$

3. We have

$$\begin{aligned} \sum_{i,j=1}^m a_i a_j c(i-j) &= \sum_{i,j=1}^m a_i a_j \text{Cov}(X_i, X_j) = \sum_{i,j=1}^m a_i a_j (\mathbb{E}[X_i X_j] - \mu^2) \\ &= \sum_{i,j=1}^m a_i a_j \mathbb{E}[X_i X_j] - \left( \sum_{i=1}^m a_i \mu \right)^2 \\ &= \mathbb{E} \left[ \left( \sum_{i=1}^m a_i X_i \right)^2 \right] - \left( \sum_{i=1}^m a_i \mathbb{E}[X_i] \right)^2 = \text{Var} \left( \sum_{i=1}^m a_i X_i \right) \geq 0. \end{aligned}$$

□

**Lemma 2.** *The empirical autocovariance matrix  $\widehat{C}_n$  is positive semi-definite:*

$$\forall n \in \mathbb{N}, \forall a_1, \dots, a_n \in \mathbb{R} : \sum_{i,j=1}^n a_i a_j \widehat{c}(i-j) \geq 0.$$

*Proof.* Set  $Y_i = (X_i - \widehat{\mu}_n) \mathbf{1}_{(1 \leq i \leq n)}$ . Then,

$$\begin{aligned} \sum_{i,j=1}^n a_i a_j \widehat{c}(i-j) &= \frac{1}{n} \sum_{i,j=1}^n a_i a_j \sum_{l=1}^{n-|i-j|} (X_l - \widehat{\mu}_n)(X_{l+|i-j|} - \widehat{\mu}_n) \\ &= \frac{1}{n} \sum_{l \in \mathbb{Z}} \sum_{i,j=1}^n a_i a_j Y_l Y_{l+|i-j|} = \frac{1}{n} \sum_{l' \in \mathbb{Z}} \sum_{i,j=1}^n a_i a_j Y_{l'-i} Y_{l'-j} \\ &= \frac{1}{n} \sum_{l' \in \mathbb{Z}} \left( \sum_{i=1}^n a_i Y_{l'-i} \right)^2 \geq 0. \end{aligned}$$

□

**Remark 4.** *In order to have that  $\widehat{C}_n$  is positive semi-definite it is essential that the prefactor before the sum in  $\widehat{c}(k)$  does not depend on  $k$ .*